

FALSE-ALARM REGULATION FOR TARGET DETECTION IN HYPERSPECTRAL IMAGING

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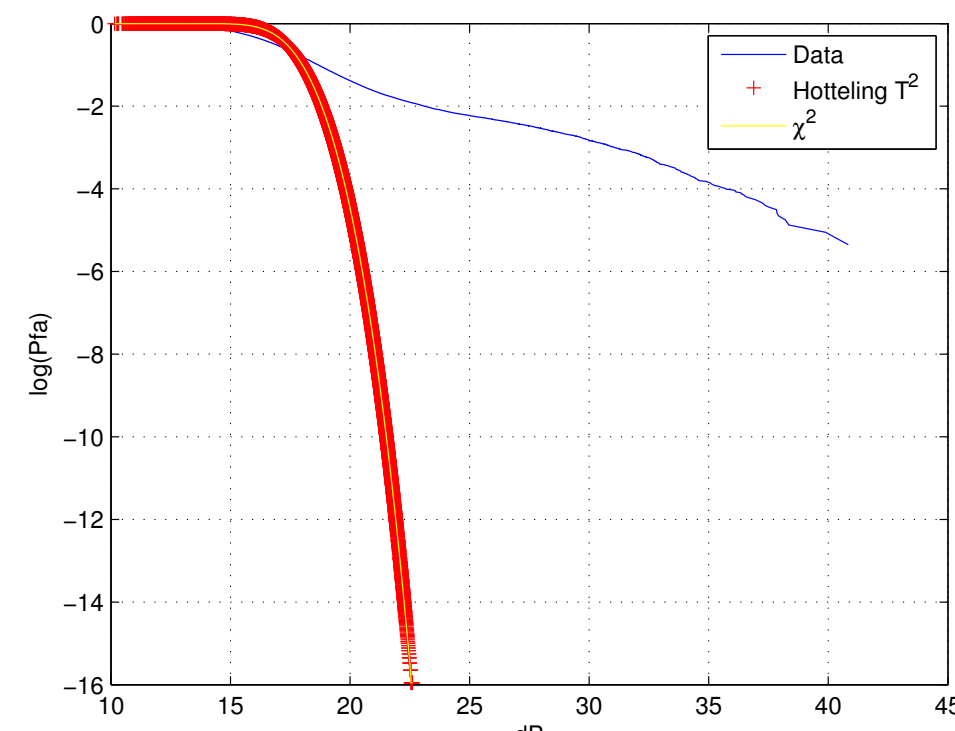
PROBLEMS DESCRIPTION

DETECTION OF TARGETS IN HYPERSPECTRAL IMAGES

To detect targets (characterized by a given spectral signature p) - Regulation of False Alarm.

The hyperspectral data are **positive** as they represent radiance or reflectance.

- In the adaptive detection framework, a mean vector and has to be included in the statistical model and estimated jointly with the covariance matrix,
- Some hyperspectral data are proven to be **spatially heterogeneous** in intensity and/or **cannot be only characterized by Gaussian statistic**.



COMPLEX NORMAL DISTRIBUTION

A m -dimensional vector x has a complex normal distribution, and if the probability density function exists, it is of the form:

$$f_x(x) = \pi^{-m} |\Sigma|^{-1} \exp\{-(x - \mu)^H \Sigma^{-1} (x - \mu)\}.$$

\nwarrow covariance matrix \swarrow mean vector

The resulting Maximum Likelihood Estimates are : $\hat{\mu}_{SMV} = \frac{1}{N} \sum_{i=1}^N x_i$ $\hat{\Sigma}_{SCM} = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})(x_i - \hat{\mu})^H$

COMPLEX WISHART DISTRIBUTION

Let x_1, \dots, x_N be an IID N-sample, where $x_i \sim \mathcal{CN}(\mu, \Sigma)$. And let $\hat{\mu} = \hat{\mu}_{SMV}$ and $\hat{W} = N \hat{\Sigma}_{SCM}$ referred to as the **Wishart** matrix. Thus, one has:

- $\hat{\mu}$ and \hat{W} are independently distributed;
- $\hat{\mu} \sim \mathcal{CN}\left(\mu, \frac{1}{N} \Sigma\right)$;
- $\hat{W} \sim \mathcal{CW}(N-1, \Sigma)$ is **Wishart** distributed with $N-1$ degrees of freedom.

TARGET DETECTION SCHEMES - AMF

- Derived under Gaussian hypothesis,
- It is the optimal linear filter in terms of SNR maximization under Gaussian assumption,
- Its false alarm is independent of the covariance matrix, **CFAR-matrix**.

MATCHED FILTER

Known covariance matrix and mean vector

$$\Lambda_{MF} = \frac{|p^H \Sigma^{-1} (x - \mu)|^2}{(p^H \Sigma^{-1} p)} \underset{H_0}{\gtrless} \lambda$$

PFA-THRESHOLD RELATIONSHIP

$$PFA_{MF} = \exp(-\lambda)$$

ADAPTIVE MATCHED FILTER

Unknown covariance matrix and known mean vector

$$\Lambda_{AMF}^{(N)} = \frac{|p^H \hat{\Sigma}^{-1} (x - \mu)|^2}{(p^H \hat{\Sigma}^{-1} p)} \underset{H_0}{\gtrless} \lambda \quad PFA_{AMF} = {}_2F_1\left(N-m+1, N-m+2; N+1; -\frac{\lambda}{N}\right)$$

ADAPTIVE MATCHED FILTER

Unknown covariance matrix and mean vector

$$\Lambda_{AMF}^{(N)} = \frac{|p^H \hat{\Sigma}^{-1} (x - \hat{\mu})|^2}{(p^H \hat{\Sigma}^{-1} p)} \underset{H_0}{\gtrless} \lambda$$

Firstly remark that as we jointly estimate the mean and the covariance matrix we lose a degree of freedom.

Let us now consider the AMF replacing $\hat{\Sigma}_{SCM}$ by the Wishart matrix \hat{W}_{N-1} :

$$\Lambda_{AMF}^{(N)} = N \frac{|p^H \hat{W}_{N-1}^{-1} (x - \hat{\mu})|^2}{(p^H \hat{W}_{N-1}^{-1} p)}$$

Since $\hat{\mu} \sim \mathcal{CN}\left(\mu, \frac{1}{N} \Sigma\right)$, one has $x - \hat{\mu} \sim \mathcal{CN}\left(0, \frac{N+1}{N} \Sigma\right)$.

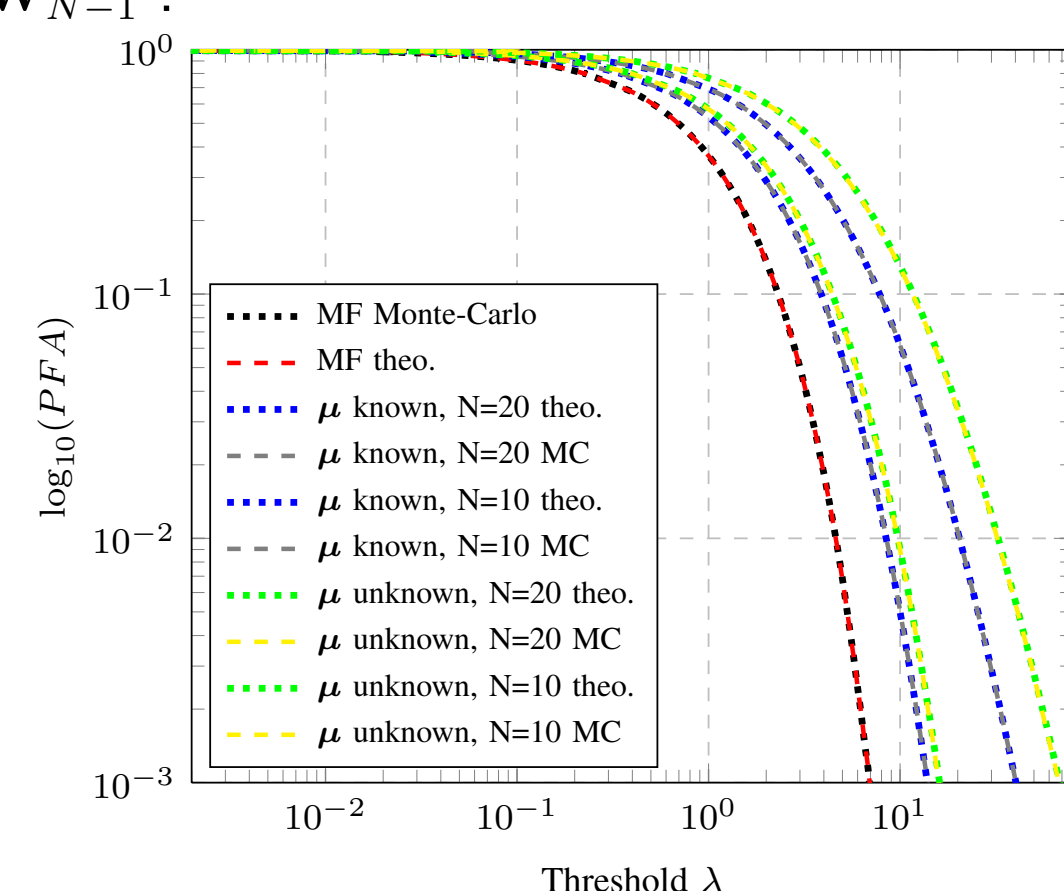
This can be equivalently rewritten as :

$$y = \sqrt{N/(N+1)} (x - \hat{\mu}) \sim \mathcal{CN}(0, \Sigma)$$

When replacing it on the test we obtain:

$$\Lambda_{AMF}^{(N)} = N \frac{N+1}{N} \frac{|p^H \hat{W}_{N-1}^{-1} y|^2}{(p^H \hat{W}_{N-1}^{-1} p)} = \frac{(N+1)}{(N-1)} \Lambda_{AMF}^{(N-1)}$$

$$PFA_{AMF} = {}_2F_1\left(N-m, N-m+1; N; -\frac{\lambda}{N+1}\right)$$



TARGET DETECTION SCHEMES - ANMF

- Derived under Gaussian hypothesis,
- It is invariant under scale change of the observation vector,
- Its false alarm is independent of the covariance matrix, **CFAR-matrix**.

NORMALIZED MATCHED FILTER

Known covariance matrix and mean vector

$$\Lambda_{NMF} = \frac{|p^H \Sigma^{-1} (x - \mu)|^2}{(p^H \Sigma^{-1} p) ((x - \mu)^H \Sigma^{-1} (x - \mu))} \underset{H_0}{\gtrless} \lambda$$

PFA-THRESHOLD RELATIONSHIP

$$PFA_{NMF} = (1 - \lambda)^{(m-1)}$$

ADAPTIVE NORMALIZED MATCHED FILTER

Unknown covariance matrix and known mean vector

$$\Lambda_{ANMF}^{(N)} = \frac{|p^H \hat{\Sigma}^{-1} (x - \mu)|^2}{(p^H \hat{\Sigma}^{-1} p) ((x - \mu)^H \hat{\Sigma}^{-1} (x - \mu))} \underset{H_0}{\gtrless} \lambda$$

$$PFA_{ANMF} = (1 - \lambda)^{N-m+1} {}_2F_1(N-m+2, N-m+1; N+1; \lambda)$$

ADAPTIVE NORMALIZED MATCHED FILTER

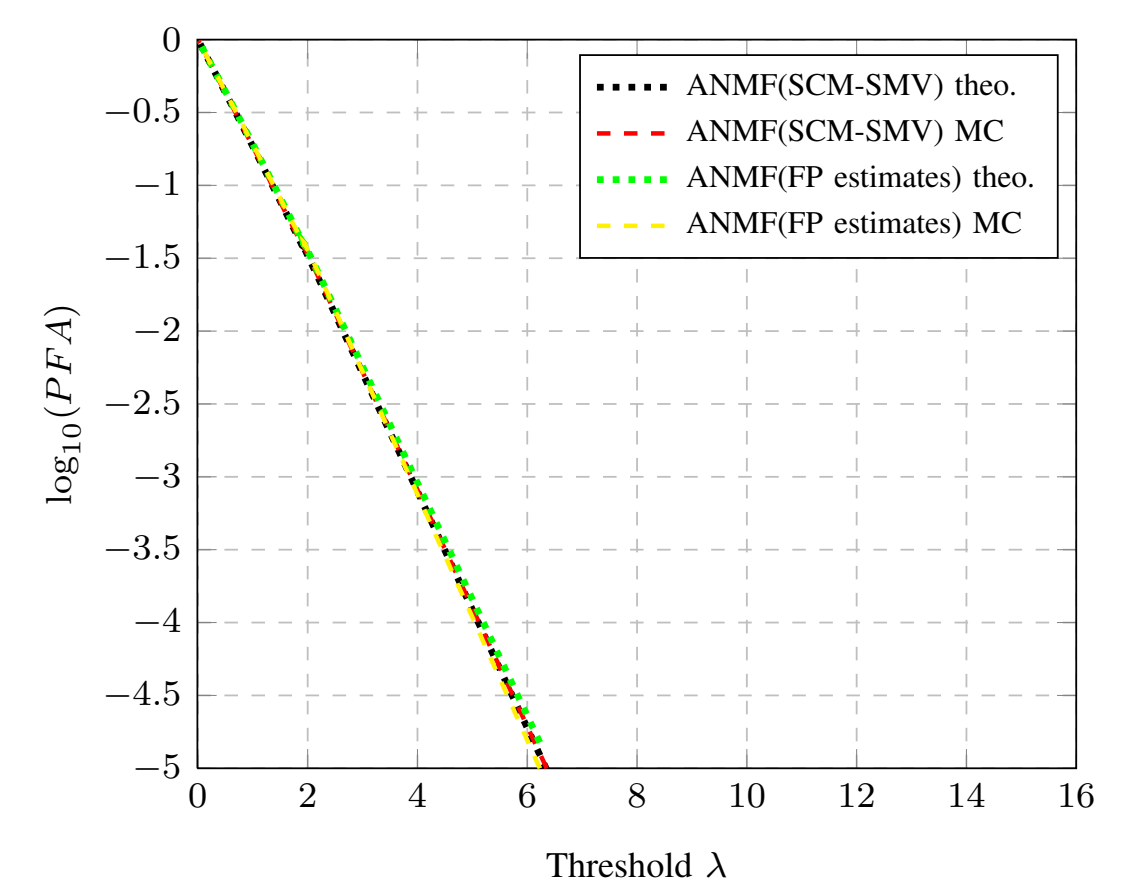
Unknown covariance matrix and mean vector

$$\Lambda_{ANMF} = \frac{|p^H \hat{\Sigma}^{-1} (x - \hat{\mu})|^2}{(p^H \hat{\Sigma}^{-1} p) ((x - \hat{\mu})^H \hat{\Sigma}^{-1} (x - \hat{\mu}))} \underset{H_0}{\gtrless} \lambda$$

Due to the normalization term $(x - \hat{\mu})^H \hat{\Sigma}^{-1} (x - \hat{\mu})$, the correction factor $(N+1)/N$ appears both at the numerator and at the denominator and consequently, it disappears.

Since the detector is homogeneous in terms of covariance matrix, the factor N also disappears.

$$PFA_{ANMF} = (1 - \lambda)^{N-m} {}_2F_1(N-m+1, N-m; N; \lambda)$$



ROBUST TARGET DETECTION - ANMF

In order to take into account **heterogeneity** and **non-Gaussianity** for background modeling, the class of **Elliptical Distribution Model** is considered:

$$f_x(x) = |\Sigma|^{-1} h_m((x - \mu)^H \Sigma^{-1} (x - \mu))$$

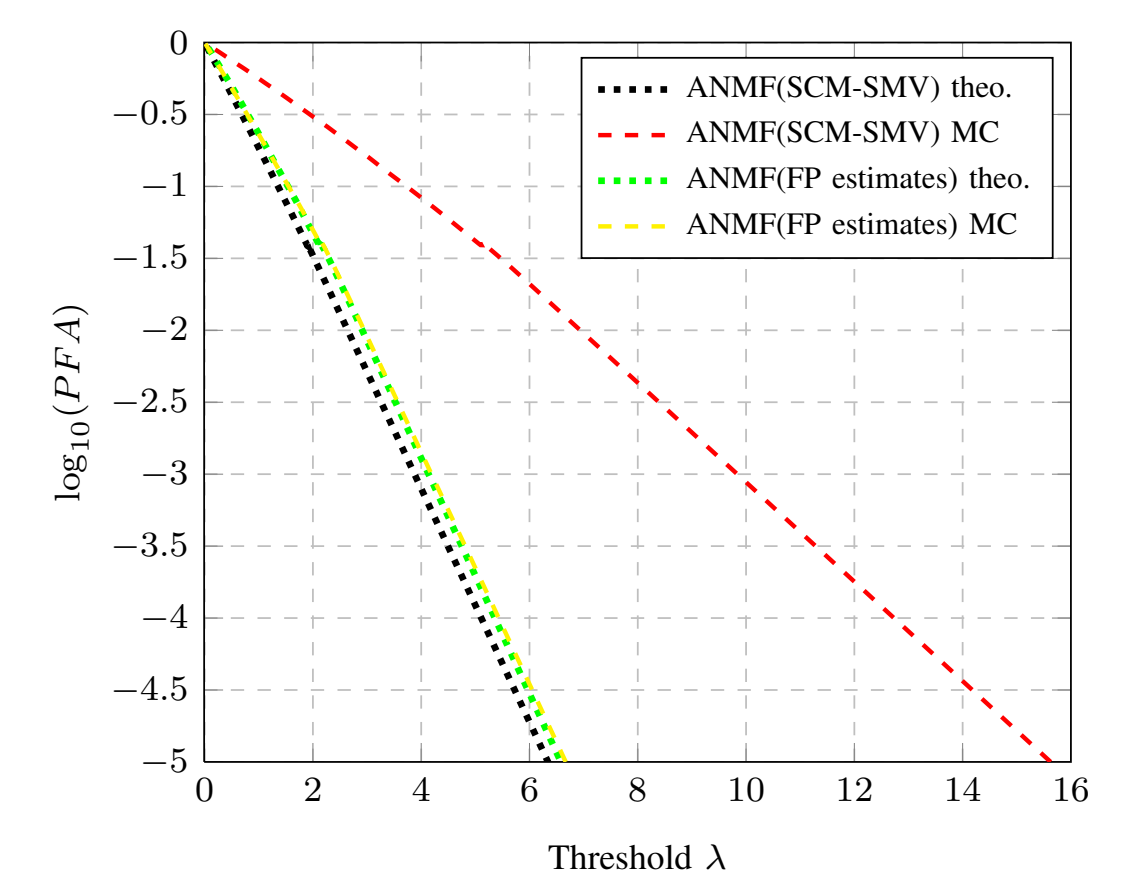
\nwarrow density generator

- Due to its invariance properties ANMF detector provide the best detection results in non-Gaussian environment,
- One has to introduce Robust Estimation procedures to achieve robustness in the detection scheme.

FIXED POINT ESTIMATORS

$$\hat{\mu}_{FP} = \frac{\sum_{i=1}^N \frac{x_i}{(x_i - \hat{\mu}_{FP})^H \hat{\Sigma}_{FP}^{-1} (x_i - \hat{\mu}_{FP})^{1/2}}}{\sum_{i=1}^N \frac{1}{(x_i - \hat{\mu}_{FP})^H \hat{\Sigma}_{FP}^{-1} (x_i - \hat{\mu}_{FP})^{1/2}}}, \quad \hat{\Sigma}_{FP} = \frac{m}{N} \sum_{i=1}^N \frac{(x_i - \hat{\mu}_{FP})(x_i - \hat{\mu}_{FP})^H}{(x_i - \hat{\mu}_{FP})^H \hat{\Sigma}_{FP}^{-1} (x_i - \hat{\mu}_{FP})}$$

- This estimate does not depend on the elliptical distribution density generator,
- The Fixed Point Matrix Estimate is consistent, unbiased, asymptotically Gaussian and, for N large enough, it behaves as a Wishart matrix with $\frac{m}{m+1}N$ degrees of freedom.



$$PFA_{ANMF-FP} = (1 - \lambda)^{\frac{m}{m+1}(N-1)-m+1} {}_2F_1\left(\frac{m}{m+1}(N-1)-m+2, \frac{m}{m+1}(N-1)-m+1; \frac{m}{m+1}(N-1)+1; \lambda\right)$$

CONCLUSIONS

- The AMF and the ANMF have been analyzed in the case where both the covariance matrix and the mean vector are unknown and need to be estimated,
- Closed-form expressions for "PFA-threshold" relationships have been derived under Gaussian assumptions,
- Additionally, Kelly detector has been studied for non-zero mean Gaussian distribution but non-closed form for "PFA-threshold" relationship can be obtained,
- In Elliptical distributions framework, the joint robust location and scale estimators have been proposed and they provide better false-alarm regulation and an improvement for detection in heterogeneous and/or non-Gaussian background.