## Asymptotic Detection Performance of the Robust ANMF

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## Motivations

Let us considering the following binary hypotheses test:

$$\begin{cases} H_0: \mathbf{y} = \mathbf{c}, & \mathbf{y}_i = \mathbf{c}_i, \quad i = 1, \dots, N \\ H_1: \mathbf{y} = \alpha \mathbf{p} + \mathbf{c}, & \mathbf{y}_i = \mathbf{c}_i, \quad i = 1, \dots, N \end{cases},$$

where c is an additive noise,  $\{c_i\}_{i \in [1,N]}$  are N signal-free secondary data, p a known steering vector and where  $\alpha$  is the unknown amplitude of the target.

In partially homogeneous Gaussian environment (i.e.  $\{\mathbf{c}_i\}_{i \in [1,N]} \sim \mathbb{CN}(\mathbf{0}_m, \mathbf{M})$ ,  $\mathbf{c} \sim \mathbb{CN}(\mathbf{0}_m, \sigma^2 \mathbf{M})$ ) when  $\mathbf{M}$  is known and  $\sigma^2$  unknown, the GLRT is the well known Normalized Matched Filter [L. Scharf]:

$$H(\mathbf{M}) = \frac{|\mathbf{p}^{H}\mathbf{M}^{-1}\mathbf{y}|^{2}}{(\mathbf{p}^{H}\mathbf{M}^{-1}\mathbf{p})(\mathbf{y}^{H}\mathbf{M}^{-1}\mathbf{y})}$$

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## Motivations

When an estimate  $\widehat{\mathbf{M}}_{SCM} = \frac{1}{N} \sum_{k=1}^{N} \mathbf{c}_k \mathbf{c}_k^H$  of  $\mathbf{M}$  is plugged into the NMF (two-step GLRT), this results in the so-called ANMF [S. Kraut] whose distribution is given by:

$$p_{H(\widehat{\mathbf{M}}_{SCM})}(x) = \frac{\Gamma(N+1) e^{-\delta}}{\Gamma(N-m+1) \Gamma(m-1)} \int_{0}^{1} u^{N-m+1} \frac{(1-u)^{m-1} (1-x)^{N-m}}{(1-ux)^{N-m+2}} \times {}_{1}F_{1}\left(N-m+2, 1; \frac{\delta x (1-u)}{1-x u}\right) du.$$
(1)

Performances of the NMF and ANMF can be easily described in terms of:

- Probability of False Alarm  $P_{fa}$  versus the detection threshold  $\lambda$  ( $\delta = 0$ ),
- Probability of Detection  $P_d$  versus the SNR  $\delta = \alpha^2 \mathbf{p}^H \mathbf{M}^{-1} \mathbf{p} / \sigma^2$ .

## Motivations

Under more severe environment (spikyness, heterogeneity of the background, outliers in secondary data, ...), the performance of ANMF is dramatically degraded. The noise c and secondary data  $\{c_i\}_{i \in [1,N]}$  cannot be described by conventional Gaussian PDF:

- need to characterize the environment statistics using more general models: Spherically Invariant Random Vectors (SIRV) or Complex Elliptically Symmetric (CES) distributions
- need to propose robust estimators of the background parameters (e.g. covariance matrix): *M*-estimators

The goal of this paper is to derive under both  $H_0$  and  $H_1$  hypotheses the asymptotic distributions (N not too small) of the robust ANMF built with any M-estimator  $\widehat{\mathbf{M}}$  when the noise and secondary data are modelled by Complex Elliptically Symmetric (CES) distributions:

$$\mathcal{H}(\widehat{\mathbf{M}}) = \frac{\left|\mathbf{p}^{H} \, \widehat{\mathbf{M}}^{-1} \, \mathbf{y}\right|^{2}}{\left(\mathbf{p}^{H} \, \widehat{\mathbf{M}}^{-1} \, \mathbf{p}^{H}\right) \, \left(\mathbf{y}^{H} \, \widehat{\mathbf{M}}^{-1} \, \mathbf{y}\right)}.$$

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## Modeling the Background

Let c be a complex circular random vector of length *m*. c has a complex elliptically symmetric (CES) distribution ( $CE(\mu, \mathbf{M}, h_m)$ ) if its PDF is

$$g_{\mathbf{c}}(\mathbf{c}) = |\mathbf{M}|^{-1} h_m \left( (\mathbf{c} - \boldsymbol{\mu})^H \mathbf{M}^{-1} (\mathbf{c} - \boldsymbol{\mu}) \right),$$

where  $h_m: [0,\infty) \to [0,\infty)$  is the density generator.

•  $\mu$  is the statistical mean (generally known or = 0)

M the scatter matrix

In general (finite second-order moment),  $\mathbf{M}$  is equal to the covariance matrix  $E[(\mathbf{c} - \boldsymbol{\mu}) (\mathbf{c} - \boldsymbol{\mu})^H]$  up to a scalar factor.

CES distributions *M*-estimators

## Attractive clutter modeling

#### Some important properties

- Large class of distributions: Gaussian, SIRV, MGGD, K-dist., Student-t....
- Closed under affine transformations,
- All sub-vectors of z have a CES distribution,
- CES stochastic representation theorem:  $\mathbf{c} =_d \boldsymbol{\mu} + \tau \mathbf{A} \mathbf{u}$  where the random scalar texture  $\tau \ge 0$  is independent of  $\mathbf{u}$  (*m*-vector uniformly distributed on the sphere) and characterized by its PDF  $p_{\tau}(.)$  and where  $\mathbf{M} = \mathbf{A} \mathbf{A}^{H}$ ,
- SIRV subclass stochastic representation theorem:  $\mathbf{c} =_d \boldsymbol{\mu} + \tau \mathbf{u}$  where the random scalar texture  $\tau \ge 0$  is independent of  $\mathbf{u} \sim \mathbb{CN}(\mathbf{0}_m, \mathbf{M})$  and characterized by its PDF  $p_{\tau}(.)$ .

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## Estimating the covariance matrix

Let  $(\mathbf{c}_1, ..., \mathbf{c}_N)$  be a *N*-sample ~  $CES(\mathbf{0}_m, \mathbf{M}, h_m)$  (Secondary data).

M-estimator of  $\mathbf{M}$ 

$$\widehat{\mathbf{M}} = rac{1}{N} \sum_{i=1}^{N} u\left(\mathbf{c}_{i}^{H} \,\widehat{\mathbf{M}}^{-1} \,\mathbf{c}_{i}
ight) \,\mathbf{c}_{i} \,\mathbf{c}_{i}^{H},$$

Maronna (1976), Kent and Tyler (1991)

- Existence
- Uniqueness
- Convergence of the recursive algorithm...

PDF specified  $\Rightarrow$  MLE can be derived:  $u(x) = -h'_m(x)/h_m(x)$ PDF not specified  $\Rightarrow$  general M-estimators are used instead

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## Some remarks on the *M*-estimators

- FPE and SCM are "not" (theoretically) *M*-estimators
- FPE is the most robust

FP Estimate (Tyler, 1987; Pascal, 2008)

$$\widehat{\mathbf{M}}_{FPE} = \frac{m}{N} \sum_{i=1}^{N} \frac{\mathbf{c}_{i} \, \mathbf{c}_{i}^{H}}{\mathbf{c}_{i}^{H} \, \widehat{\mathbf{M}}_{FPE}^{-1} \, \mathbf{c}_{i}}$$

- The FPE does not depend on the texture (SIRV or CES distributions)
- Existence, Uniqueness, Convergence of the recursive algorithm...
- True MLE under SIRV noise with unknown deterministic texture  $\{\tau_i\}_{i \in [1,N]}$

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## Asymptotic distribution of complex *M*-estimators

Using the results of Tyler, we derived the following results [Ollila, Mahot, 2013]:

Asymptotic distribution of M

$$\sqrt{N} \operatorname{vec}(\widehat{\mathbf{M}} - \mathbf{M}) \stackrel{d}{\longrightarrow} \mathbb{CN}\left(\mathbf{0}_{m^2}, \mathbf{C}, \mathbf{P}\right),$$

where the covariance matrix  ${\bf C}$  and the pseudo covariance matrix  ${\bf P}$  are given by:

$$\begin{split} \mathbf{C} &= \mathbf{v}_1(\mathbf{M}^* \otimes \mathbf{M}) + \mathbf{v}_2 \operatorname{vec}(\mathbf{M}) \operatorname{vec}(\mathbf{M})^H, \\ \mathbf{P} &= \mathbf{v}_1(\mathbf{M}^* \otimes \mathbf{M}) \operatorname{K} + \mathbf{v}_2 \operatorname{vec}(\mathbf{M}) \operatorname{vec}(\mathbf{M})^T, \end{split}$$

where  ${\bf K}$  is the commutation matrix and where the constant  $\nu_1$  and  $\nu_2$  are completely defined.

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# Asymptotic distribution of a function of complex *M*-estimators

• Let  $H(\mathbf{V})$  be a *r*-multivariate function on the set of Hermitian positive-definite matrices, with continuous first partial derivatives and such as  $H(\mathbf{V}) = H(\alpha \mathbf{V})$  for all  $\alpha > 0$ , e.g. the ANMF statistic, the MUSIC statistic.

#### Asymptotic distribution of $H(\mathbf{M})$

$$\sqrt{N}\left(H(\widehat{\mathbf{M}}) - H(\mathbf{M})\right) \stackrel{d}{\longrightarrow} \mathbb{C}\mathcal{N}\left(\mathbf{0}_{r}, \mathbf{C}_{H}, \mathbf{P}_{H}\right)$$

where  $\mathbf{C}_{\mathcal{H}}$  and  $\mathbf{P}_{\mathcal{H}}$  are defined as

$$\mathbf{C}_{H} = \mathbf{v}_{1} H'(\mathbf{M}) (\mathbf{M}^{T} \otimes \mathbf{M}) H'(\mathbf{M})^{H}, \mathbf{P}_{H} = \mathbf{v}_{1} H'(\mathbf{M}) (\mathbf{M}^{T} \otimes \mathbf{M}) \mathbf{K}_{m,m} H'(\mathbf{M})^{T},$$

where  $H'(\mathbf{M}) = \left(\frac{\partial H(\mathbf{M})}{\partial \mathsf{vec}(\mathbf{M})}\right)$ .

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## Two important properties of complex *M*-estimators

SCM and *M*-estimators share the same asymptotic distribution *H*(*SCM*) and *H*(*M*-estimators) share the same asymptotic distribution (differs from ν<sub>1</sub>)

	SCM	M-estimators	FP
$\nu_1$	1	$\nu_1$	(m+1)/m
ν <sub>2</sub>	0	$\nu_2$	$-(m+1)/m^2$

This important result shows that asymptotically and under Gaussian environment:

- any *M*-estimator built with *N* observations behaves like the SCM but with a slight smaller degree of freedom  $N/v_1$ ,
- any function *H* built with *M*-estimator behaves like those built with SCM but with a slight smaller degree of freedom  $N/v_1$ .

Key ideas

Correcting the degree of freedom of the *M*-estimator Exploiting the asymptotic distribution of the robust ANMF

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## A particular choice of H(.): the two-step GLRT ANMF

## Robust ANMF test (ACE, GLRT-LQ) [Conte, 1995

$$H(\widehat{\mathbf{M}}) = \Lambda_{ANMF}(\mathbf{y}, \widehat{\mathbf{M}}) = \frac{|\mathbf{p}^{H} \, \widehat{\mathbf{M}}^{-1} \, \mathbf{y}|^{2}}{(\mathbf{p}^{H} \, \widehat{\mathbf{M}}^{-1} \, \mathbf{p})(\mathbf{y}^{H} \, \widehat{\mathbf{M}}^{-1} \, \mathbf{y})} \underset{H_{0}}{\overset{H_{1}}{\gtrless}} ?$$

where  $\widehat{\mathbf{M}}$  stands for any *M*-estimators.

The ANMF is scale-invariant (homogeneous of degree 0), i.e.

$$\forall \boldsymbol{\alpha}, \boldsymbol{\beta} \in \mathbb{R} \,, \, \Lambda_{\textit{ANMF}}(\boldsymbol{\alpha} \, \mathbf{y}, \boldsymbol{\beta} \, \widehat{\mathbf{M}}) = \Lambda_{\textit{ANMF}}(\mathbf{y}, \widehat{\mathbf{M}})$$

- The ANMF test is CFAR w.r.t the covariance/scatter matrix M,
- The ANMF test is CFAR w.r.t the texture (SIRV or CES distributions)

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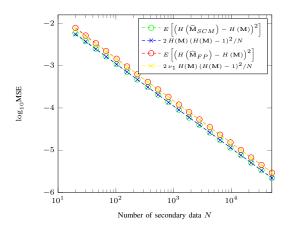
# Two different ways to derive robust ANMF asymptotic performance

- by correcting the degree of freedom of the *M*-estimator  $(N \rightarrow N/\nu_1)$  in  $p_{H(\widehat{\mathbf{M}}_{SCM})}$  presented in (1) and by conditioning on the texture PDF,
- by exploiting directly the asymptotic distribution of the ANMF [Pascal -Ovarlez 2015]:

$$H(\widehat{\mathbf{M}}) \stackrel{d}{\longrightarrow} \mathbb{CN}\left(H(\mathbf{M}), 2\frac{\mathbf{v}_1}{N}H(\mathbf{M}) \ (H(\mathbf{M})-1)^2\right).$$

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Empirical variance of the ANMF built with the SCM ( $v_1 = 1$ ) and Tyler's *M*-estimator ( $v_1 = (m+1)/m$ ) in Gaussian environment and theoretical asymptotic variance for m = 3 and  $\mathbf{M} = \mathbf{I}_3$ .

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## Correcting the degree of freedom of the *M*-estimator

Evaluation of the performance for a cell under test containing SIRV noise and for any CES secondary data.

$$P_{fa} = \mathbb{P}\left(H(\widehat{\mathbf{M}}) \ge \lambda | H_0\right), \qquad P_d = \mathbb{P}\left(H(\widehat{\mathbf{M}}) \ge \lambda | H_1\right)$$

$$P_{fa} = (1 - \lambda)^{N/\nu_1 - m + 1} {}_2F_1 \left( N/\nu_1 - m + 2, N/\nu_1 - m + 1; N/\nu_1 + 1; \lambda \right) ,$$

$$P_{d} = 1 - \int_{0}^{+\infty} d\tau \int_{0}^{1} du \int_{0}^{\lambda} u^{N/\nu_{1} - m + 1} \frac{(1 - u)^{m - 1} (1 - x)^{N/\nu_{1} - m}}{(1 - u x)^{N/\nu_{1} - m + 2}} e^{-\delta/\tau}$$

$$\times \frac{\Gamma(N/\nu_{1} + 1)}{\Gamma(N/\nu_{1} - m + 1) \Gamma(m - 1)} {}_{1}F_{1} \left( N/\nu_{1} - m + 2, 1; \frac{\delta}{\tau} \frac{x (1 - u)}{1 - x u} \right) p_{\tau}(\tau) dx$$

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Exploiting the asymptotic distribution of the robust ANMF

$$H(\widehat{\mathbf{M}}) \stackrel{d}{\longrightarrow} \mathbb{CN}\left(H(\mathbf{M}), 2\frac{\mathbf{v}_1}{N}H(\mathbf{M}) \left(H(\mathbf{M}) - 1\right)^2\right)$$

The distribution of  $H(\widehat{\mathbf{M}})$  is conditioned to the distribution  $p_{H(\mathbf{M})}$  of  $H(\mathbf{M})$ :

• the cell under test contains Gaussian noise:

$$p_{H(\mathbf{M})}(u) = e^{-\delta} \beta_{1,m-1}(u) {}_{1}F_{1}(m,1;u\,\delta).$$

• the cell under test contains SIRV noise:

$$p_{H(\mathbf{M})}(u) = \int_0^\infty e^{-\delta/\tau} \,\beta_{1,m-1}(u) \,_1F_1\left(m,1;\frac{u\,\delta}{\tau}\right) \,p_{\tau}(\tau) \,d\tau\,.$$

• the cell under test contains general CES noise: No closed-form under  $H_1$ . The same as SIRV noise under  $H_0$ .

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## Exploiting the asymptotic distribution of the robust ANMF

Evaluation of the performance for a cell under test containing Gaussian noise and for any CES secondary data.

$$P_{fa} = \mathbb{P}\left(H(\widehat{\mathbf{M}}) \ge \lambda | H_0\right), \qquad P_d = \mathbb{P}\left(H(\widehat{\mathbf{M}}) \ge \lambda | H_1\right)$$

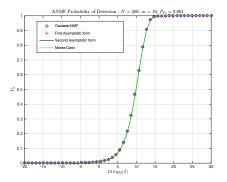
$$P_{\rm fa} = 1 - \int_0^1 \beta_{1,m-1}(x) \, \Phi\left(\frac{\sqrt{N} \, (\lambda - x)}{\sqrt{2 \, \nu_1 \, x \, (x - 1)^2}}\right) \, dx$$

$$P_{d} = 1 - \int_{0}^{1} \beta_{1,m-1}(x) e^{\delta(x-1)} {}_{1}F_{1}(1-m,1;-x\,\delta) \Phi\left(\frac{\sqrt{N}(\lambda-x)}{\sqrt{2\nu_{1}x(x-1)^{2}}}\right) dx$$

where  $\Phi(.)$  is the cumulative distribution of the Normal distribution.

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#### Ex: K-distributed secondary data and Gaussian noise in the cell under test.



Comparison between  $P_d$  and SNR  $\delta$  relationships for the ANMF built with Tyler's estimator, m = 10, N = 500 and  $P_{fa} = 10^{-3}$ ,  $\mathbf{p} = [1, ..., 1]^T$ ,  $\{\mathbf{y}_i\}_{i \in [1,N]} \sim K_v$  where  $K_v$  is a K-distribution with shape v = 0.1. and  $\mathbf{y} \sim C\mathcal{N}(\alpha \mathbf{p}, \mathbf{M})$  where  $\mathbf{M} = \left(\rho^{|i-j|}\right)_{i,j}$  with  $\rho = 0.5$ 

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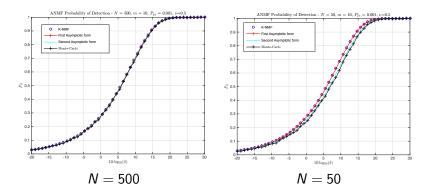
## Exploiting the asymptotic distribution of the robust ANMF

Evaluation of the performance for a cell under test containing SIRV noise with texture  $\sim p_{\tau}(.)$  and for any CES secondary data.

$$P_{\textit{fa}} = \mathbb{P}\left(H(\widehat{\mathbf{M}}) \geq \lambda | H_0\right), \qquad P_d = \mathbb{P}\left(H(\widehat{\mathbf{M}}) \geq \lambda | H_1\right)$$

where  $\Phi(\boldsymbol{.})$  is the cumulative distribution of the Normal distribution.

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Comparison between  $P_d$  and SNR  $\delta$  relationships for the NMF, the ANMF built with Tyler's estimator and its asymptotic form, m = 10,  $v_1 = 1.1$  and  $P_{fa} = 10^{-3}$ ,  $\mathbf{p} = [1, \ldots, 1]^T$ ,  $\mathbf{y} = \alpha \, \mathbf{p} + \mathbf{c}$  where  $\mathbf{c} \sim K_v$  where  $K_v$  is a multivariate K-distribution with shape parameter v = 0.5 and covariance matrix  $\mathbf{M} = \left(\rho^{|i-j|}\right)_{i,i}$  with  $\rho = 0.5$ .

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Two asymptotic approximations of the corresponding robust ANMF distribution have been derived following different approaches:

- First asymptotic distribution is based on the correction of the degrees of freedom of *M*-estimators
- Second asymptotic distribution is based on the direct exploitation of the asymptotic distribution of the ANMF

These results provide a very good approximation of the robust ANMF distribution in CES environment even for a small number of observations and have been applied to theoretically regulate the false alarm probability and to evaluate the detection performance.

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